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Dynamics | Nancy Jo Getson

Solution: i) (3 points) In polar coordinates $\vec{r} = r\hat{e}_r$: (5 points)

The velocity vector is calculated as $\vec{v} = \frac{d\vec{r}}{dt} = \frac{dr}{dt}\hat{e}_r + r\frac{d\hat{e}_r}{dt} = \frac{dr}{dt}\hat{e}_r + r\dot{\theta}\hat{e}_\theta$; where we use the product rule for derivatives. Furthermore, the unit

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vectors in polar coordinates, \hat{e}_r and \hat{e}_θ , satisfy $\frac{d\hat{e}_r}{dt} = -\dot{\theta}\hat{e}_\theta$; $\frac{d\hat{e}_\theta}{dt} = \dot{\theta}\hat{e}_r$: (5 points) Similarly, we compute the acceleration as $\vec{a} = \frac{d\vec{v}}{dt} = \frac{d^2r}{dt^2}\hat{e}_r - r\dot{\theta}^2\hat{e}_r + 2\dot{r}\dot{\theta}\hat{e}_\theta + r\ddot{\theta}\hat{e}_\theta$

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Dynamics

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Examinations. We regret to announce that EN4 will have a midterm exam and a final exam. MIDTERM: Thursday March 5, IN CLASS. (we have occasionally moved the midterm to Tuesday of the same week at students request because of midterms in other large

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classes. We will conduct an in-class poll to see if this would be helpful).

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